

DESCRIPTION

The waterproof CAN I/O PLC Waterproof PRO V2 with 15 inputs and outputs convinces by the various application possibilities in numerous control applications. In addition to eight I/Os that can be configured as inputs or outputs, it offers six analog and two digital inputs.

TECHNICAL DATA

Housing	Moulded plastic, sealed
Connector	Delphi / Aptiv - 211PC249S0033
Weight	167 g
Temperature range acc. to ISO 16750-4	-40 °C...+85 °C (at +85 °C not rated power, see p. 4)
Environmental protection acc. to ISO 20653	IP 6K6K and IP6K8 when using the protection cap and corrugated tube acc. to the accessories list <u>CAUTION! Follow the mechanical instructions!</u>
Current consumption	30 mA
Over-current protection	20 A
Total inputs and outputs	15 of which 6 are analog inputs; 1 as a digital input; 8 are I/O's (4 PWM capable with integrated current measurement INA; 2 PWM capable; 2 digital outputs)
Inputs	Configurable as: Digital input; Analog input (0...11.3 V); Current input (500 Ω against GND); 10 kΩ pull up against KL30
Outputs	Configurable as: Digital output, positive switching (high side) PWM output (3 Hz...500 Hz)
Supply voltage	9...32 V; 12 V (code B) and 24 V (code E), acc. to ISO 16750-2
Overvoltage protection	≥ 33 V
Quiescent current	138 µA (at 24 V); 875 µA (at 12 V)
Reverse polarity protection	yes
CAN interfaces	CAN bus interface 2.0 A/B, ISO 11898-2 compliant

REGULATORY APPROVALS AND TESTING

E1 approval	10 R - 05 7992
Electrical tests	According to ISO 16750-2 or -4: Short circuit protection (except RS232 interface) Reversed voltage Pin/connector interruption Overvoltage at +65 °C Operation/storage test at +85 °C Operation/storage test at -40 °C Superimposed alternating voltage Slow decrease and increase of supply voltage Momentary drop in supply voltage Reset behavior at voltage drop According to ISO 7637-2: Pulse 1, 2a, 2b, 3a, 3b

SOFTWARE/PROGRAMMING

Programming System

MRS APPLICS STUDIO

The Applics Studio is the new development and tool platform for our assemblies. Program your MRS controls quickly and easily with our stand-alone software. The focus is on your application.



INPUT FEATURES - SUMMARY

Pin A3, A4, A5, A6, B6, C4	Analog inputs Resolution	12 Bit	Pin B3, B5	Digital input Resolution	12 Bit
Voltage input 0...11.3 V (see A)	Input resistance Input frequency Accuracy	22,6 kΩ f ₁ *= 70 Hz ± 3 %	Digital input positive (see E)	Turn-on threshold Turn-off threshold	6,6 V 4,7 V
Current input 0...23 mA (see B)	Input resistance Conversion factor	500 Ω 1 mA ≈ 480 ± 3 Digits	Pin B1, B8, C1, C2, C3, C8	I/Os Resolution	12 Bit
Pull-Up input (see C)	Pull-up resistance	10 kΩ	Voltage input 0...11.3 V (see E)	Input resistance Input frequency Accuracy	15 kΩ f ₁ *= 70 Hz ± 3 %
¹ cutoff frequency (-3 dB)			Pin C6, C7	I/Os Resolution Accuracy	12 Bit ± 1 % full scale
			Voltage input 0...11.3 V (see E)	Input resistance Input frequency	15 kΩ f ₁ *= 70 Hz

OUTPUT FEATURES - SUMMARY

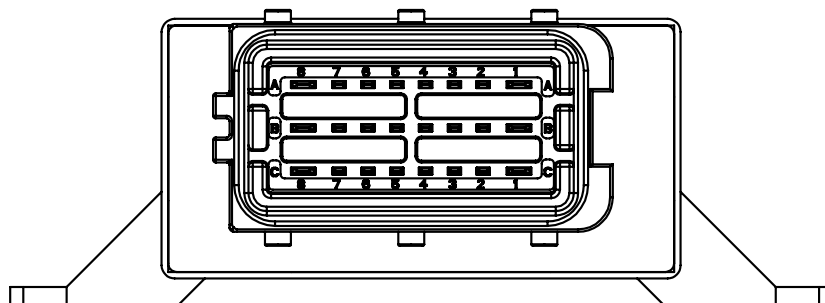
Pin C6, C7	Protective circuit for inductive loads	Optionally integrated	Pin B1, B8, C1, C2, C3, C8	Protective circuit for inductive loads	Optionally integrated
	Wire fault diagnostics	Possible via current sense		Wire fault diagnostics	Possible via current sense
	Short circuit diagnostics	Possible via current sense		Short circuit diagnostics	Possible via current sense
Digital, positive switching (high side, see E)	Switching voltage Switching current	9-32 V DC 0,02-2,5 A	Digital, positive switching (high side, see E)	Switching voltage Switching current Conversion factor current sense pins B1, C1, C2, C3 Conversion factor current sense pins B8, C6, C7, C8	9-32 V DC 0,02-2,5 A 1 Digit 2,2± 0,1 mA 1 Digit 1,2± 0,1 mA
Short circuit protection against GND and U _B	Internal overtemperature protection, latch-off can be realized by software application		PWM-output (see G)	Output frequency Duty cycle Resolution Switching current	500 Hz 0...1000 % 1 ‰ ≤ 2,5A (see page 4)
Overload protec- tion	Internal overtemperature protection, latch-off can be realized by software application			Short circuit protection against GND and U _B	Internal overtemperature protection, latch-off can be realized by software application
Pin A7 5 V Output	Max. switching current	500 mA		Overload protec- tion	Internal overtemperature protection, latch-off can be realized by software application
				Exception PIN B1, C1, C2, C3	Current sense of output current via AI_INA_PWM

PIN ASSIGNMENT POWER SUPPLY AND INTERFACES

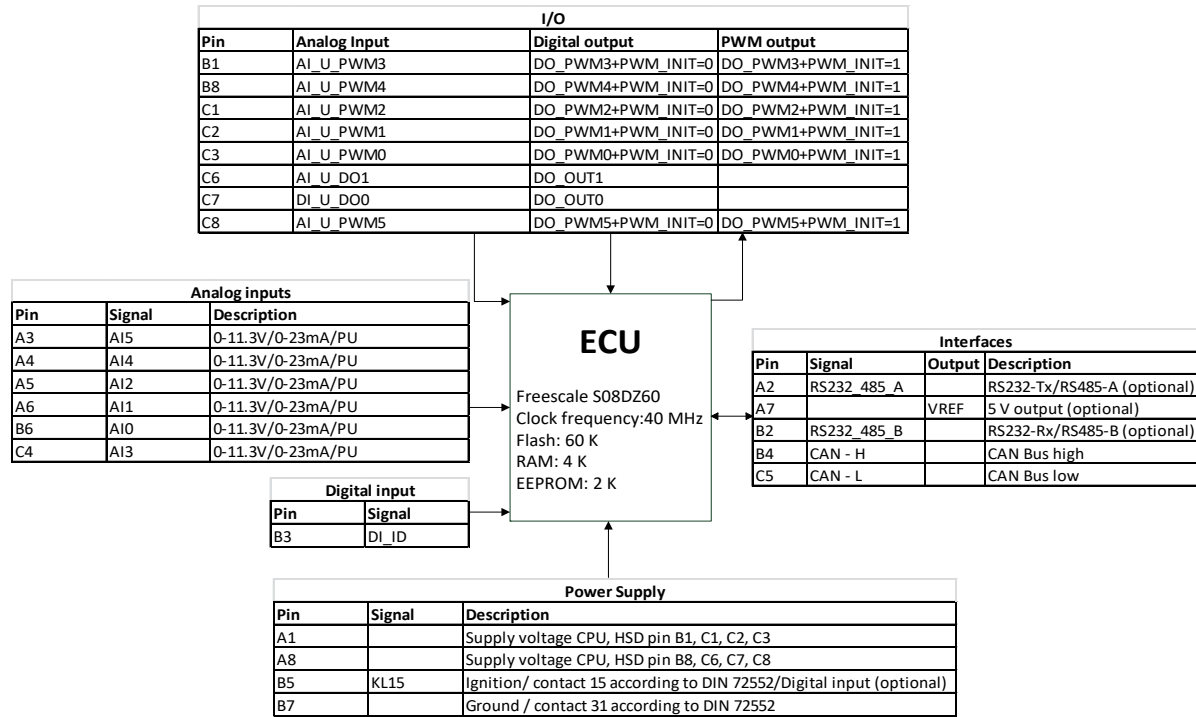
Pin	Description	Pin	Description
A1	Supply voltage for output pins B1, C1, C2, C3 supply voltage for CPU	B2	RS-485 - B / RS-232 Rx interface (assembly option see page 5)
A2	RS-485 - A / RS-232 Tx interface (assembly option see page 5)	B4	CAN bus high
A7	5 V VREF (± 2.5 % tolerance)	B5	Battery/ignition contact 15 according to DIN 72552, optional as DI (see page 5)
A8	Supply voltage for output pins B8, C6, C7, C8, supply voltage for CPU	B7	Ground/contact 31 according to DIN 72552
		C5	CAN bus low

PIN ASSIGNMENT INPUTS AND OUTPUTS

Pin	Signal	Description	Pin	Signal	Description
A3	AI5 DO_PU5 DO_PD5	Analog input 5; 0-11.3 V can also be used as: 10 kΩ pull-up Current sense 23 mA	B8	AI_U_PWM4 DO_PWM4	Analog input 4; 0-11.3 V can also be used as digital output with PWM capability
A4	AI4 DO_PU4 DO_PD4	Analog input 4; 0-11.3 V can also be used as: 10 kΩ pull-up Current sense 23 mA	C1	AI_U_PWM2 DO_PWM2	Analog input 2; 0-11.3 V can also be used as digital output with PWM capability
A5	AI2 DO_PU2 DO_PD2	Analog input 2; 0-11.3 V can also be used as: 10 kΩ pull-up Current sense 23 mA	C2	AI_U_PWM1 DO_PWM1	Analog input 1; 0-11.3 V can also be used as digital output with PWM capability
A6	AI1 DO_PU1 DO_PD1	Analog input 1; 0-11.3 V can also be used as: 10 kΩ pull-up Current sense 23 mA	C3	AI_U_PWM0 DO_PWM0	Analog input 0; 0-11.3 V can also be used as digital output with PWM capability
B1	AI_U_PWM3 DO_PWM3	Analog input 3; 0-11.3 V can also be used as digital output with PWM capability	C4	AI3 DO_PU3 DO_PD3	Analog input 3; 0-11.3 V can also be used as: 10 kΩ Pull-Up Current sense 23 mA
B3	DI_ID	Digital input	C6	AI_U_DO1 DO_OUT1	Analog input 1; 0-11.3 V can also be used as digital output
B6	AI0 DO_PU0 DO_PD0	Analog input 0; 0-11.3 V can also be used as: 10 kΩ pull-up Current sense 23 mA	C7	AI_U_DO0 DO_OUT0	Analog input 0; 0-11.3 V can also be used as digital output
			C8	AI_U_PWM5 DO_PWM5	Analog input 5; 0-11.3 V can also be used as digital output with PWM capability



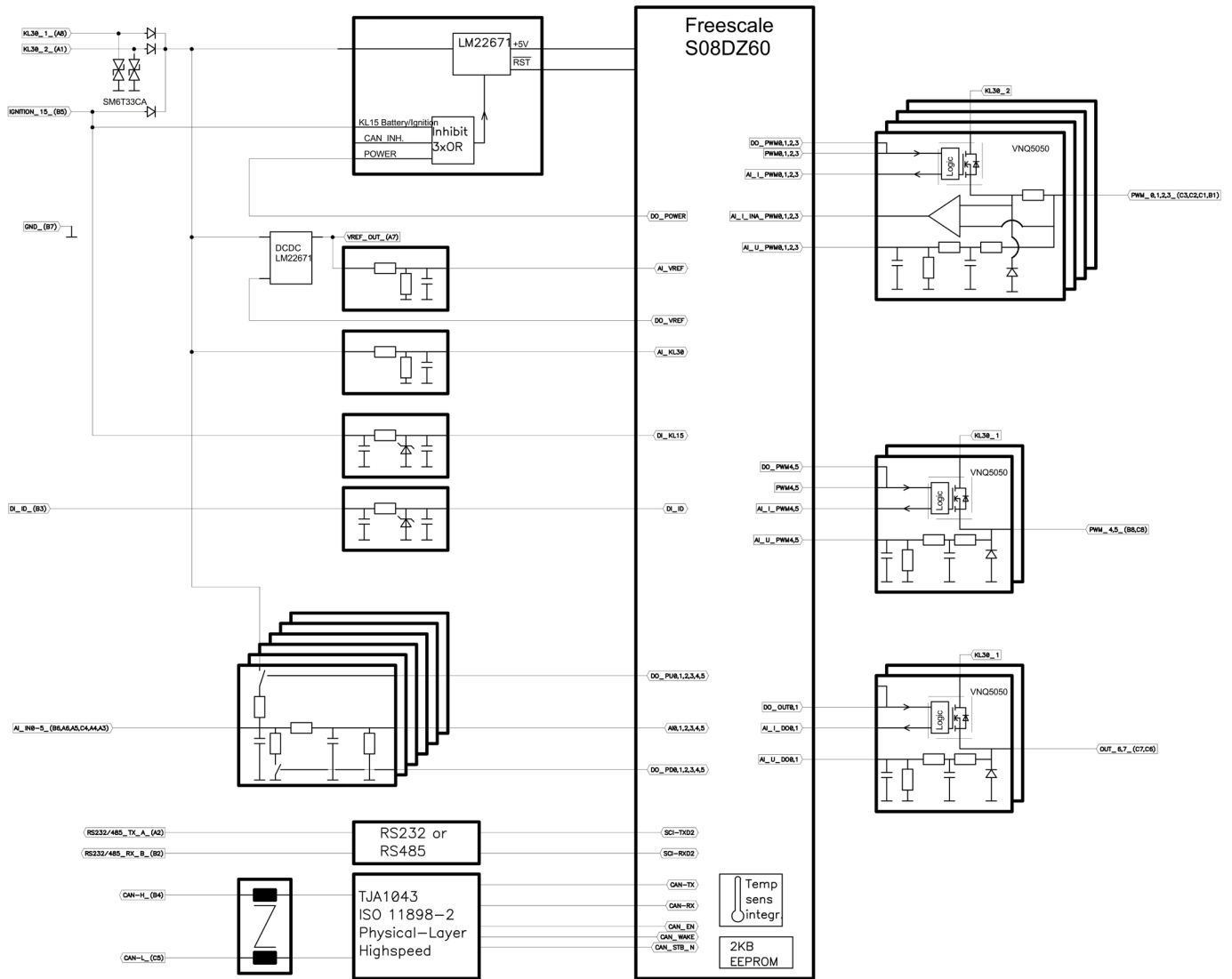
PIN FEATURE MAP



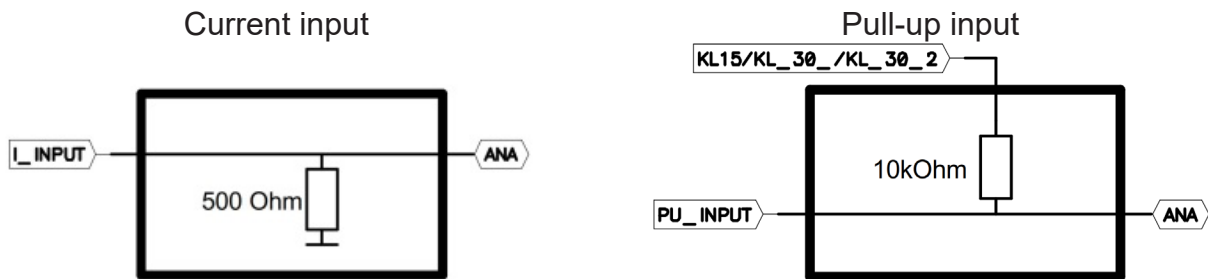
PERFORMANCE TESTS HIGH SIDE DRIVER VNQ5050AK

Test without PWM				Test with PWM			
	Test No.	Load	Endurance		Test Nr.	Load	Endurance
Endurance tests at +80 °C for digital outputs (max. 2 channels per high side driver)	1	4 x 2,5 A	Continuous	Endurance tests at +80 °C for PWM outputs with frequency=200 Hz and 90 % duty cycle (max. 2 channels per high side driver)	1	4 x 2,0 A	Continuous
	2	3 x 2,5 A 1 x 3,5 A	30 minutes		2	4 x 2,5 A	15 minutes
	3	2 x 2,5 A 2 x 3,5 A	15 minutes		3	1 x 3,5 A 3 x 2,5 A	2 minutes
	4	1 x 2,5 A 3 x 3,5 A	10 minutes		4	2 x 3,5 A	2 minutes
	5	2 x 5 A	5 minutes				

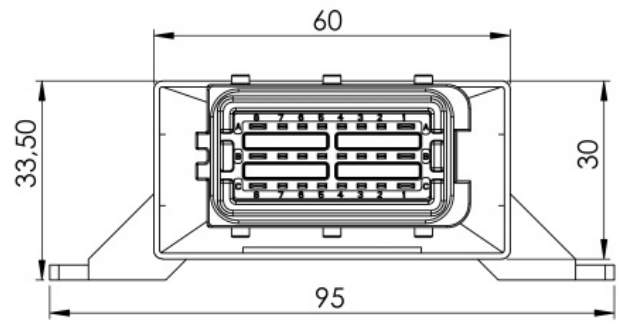
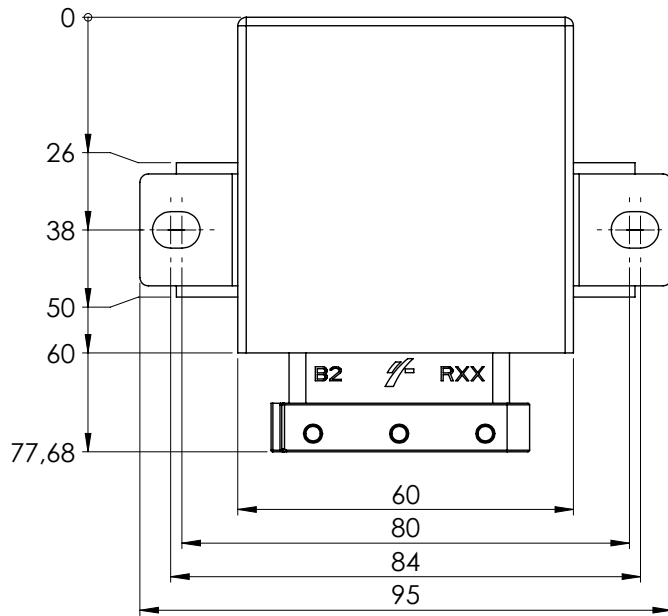
BLOCK FUNCTION DIAGRAM



BLOCK FUNCTION DIAGRAM FOR ASSEMBLY OPTIONS



TECHNICAL DRAWING IN MM [INCH], TOLERANCES ACCORDING TO ISO 2768-1 V





ASSEMBLY OPTIONS AND ORDER INFORMATION

Order number	Inputs					Outputs	CAN Bus	Wake up	Serial interface		5 V out-put	µC
	A voltage 0 – 11.3 V	B current 0 – 23 mA	C Sensor inputs 10 kΩ Pull-up	E Digital input	F I/O's (can be used as analog or digital input o ras digital output)				G PWM ≤ 500 Hz	High-Speed		
1.128.301.0000	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	B3	B1, B8, C1, C2, C3, C6, C7, C8	B1, B8, C1, C2, C3, C8	B4, C5 CAN H/L	KL 30		X	X	DZ60
1.128.301.1000	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	B3	B1, B8, C1, C2, C3, C6, C7, C8	B1, B8, C1, C2, C3, C8	B4, C5 CAN H/L	KL 15/ CAN		X	X	DZ60
1.128.321.1000	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	B3	B1, B8, C1, C2, C3, C6, C7, C8	B1, B8, C1, C2, C3, C8	B4, C5 CAN H/L	KL 15/ CAN	X		X	DZ60
1.128.301.1010	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	B3	B1, B8, C1, C2, C3, C6, C7, C8	B1, B8, C1, C2, C3, C8	B4, C5 CAN H/L	KL 15/ CAN		X	X	DZ128
1.128P.301.1000 (CANopen)	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	A3, A4, A5, A6, B6, C4	B3	B1, B8, C1, C2, C3, C6, C7, C8	B1, B8, C1, C2, C3, C8	B4, C5 CAN H/L	KL 15/ CAN		X	X	DZ60

SCIP number: 679d57de-4e64-4a9a-8bfa-1dc6f2f03830

ACCESSORIES

Description	Order number
Programming tool MRS Developers Studio	1.100.100.09
Programming Cable set CAN I/O WP	110490
Connector package CAN I/O WP	110421
Corrugated tube (outer diameter: 21.2 mm; inner diameter: 16.5 mm)	Available from independent retailers
PCAN-USB Interface	105358
Crimp terminals 2.8 mm/1-2.5 mm ²	109947
Crimp terminals 1.5 mm/1.3-2. mm ²	109949
Dummy FCI Filler Plug	110268

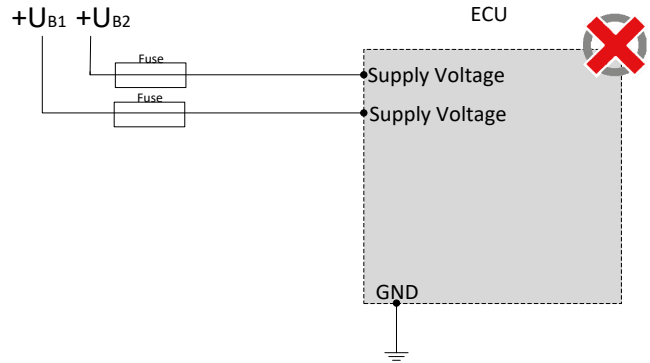
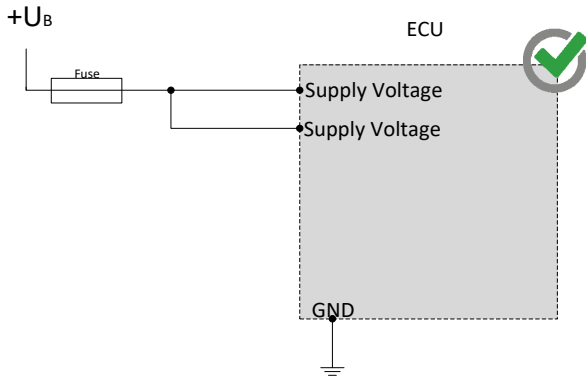


MANUFACTURER

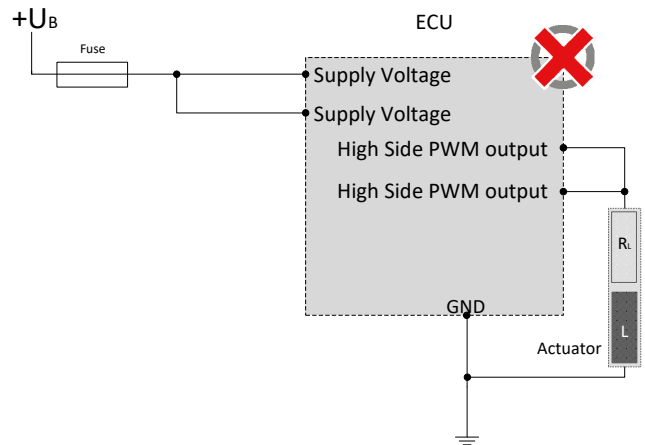
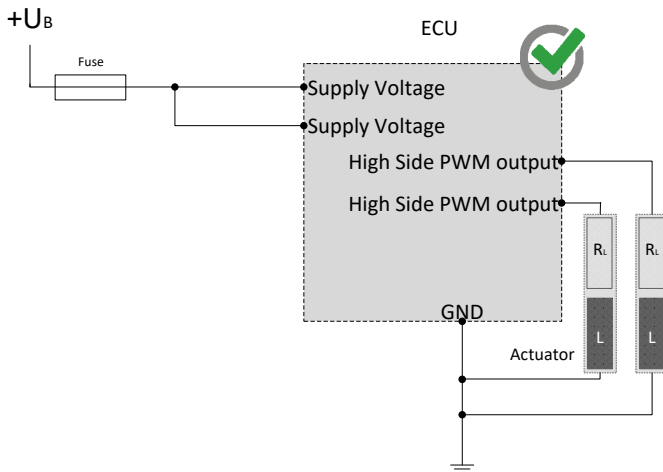
MRS Electronic, Inc.
 6680 Poe Avenue Suite 100
 Dayton OH, 45414

NOTES ON WIRING AND CABLE ROUTING

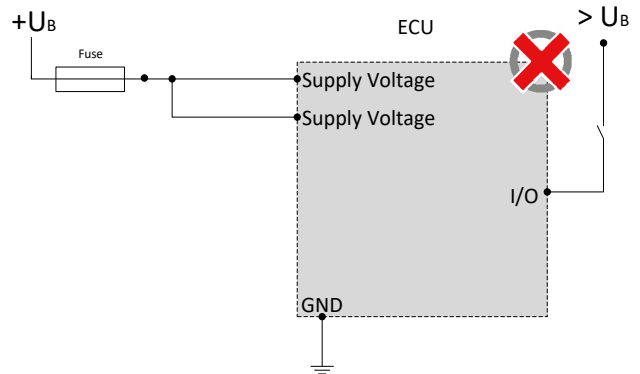
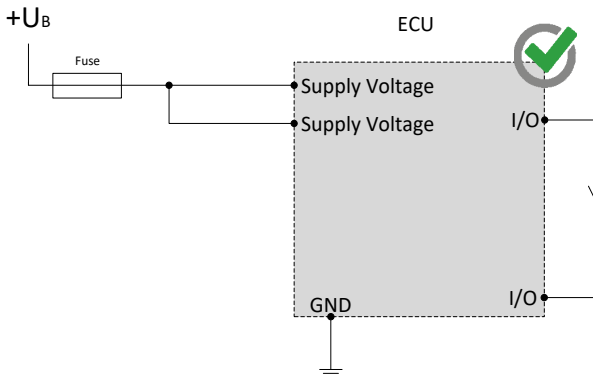
The electronic system and the power outputs of a control unit must be supplied by the same power supply system.



PWM outputs may not be connected with each other or bypassed.

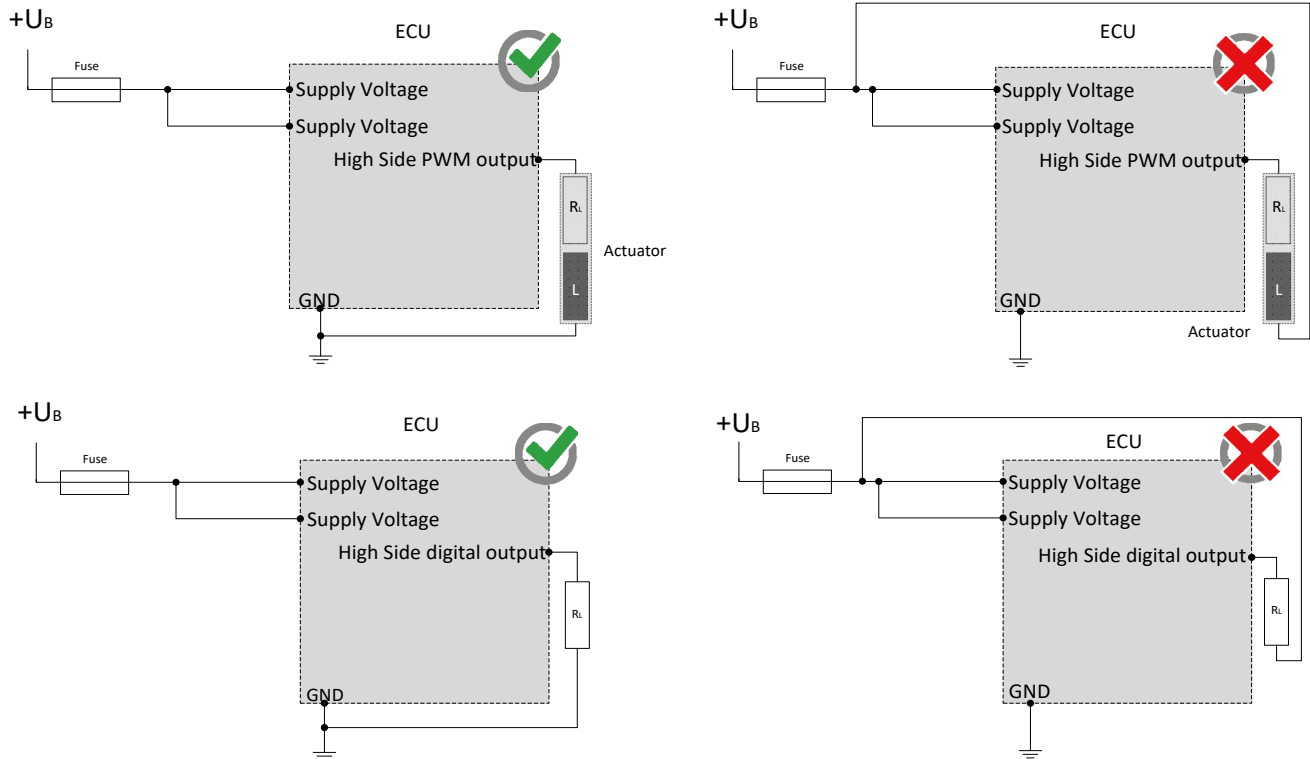


The pins (I/Os) can be used in combination and may not be switched externally against a higher voltage level than supply voltage.

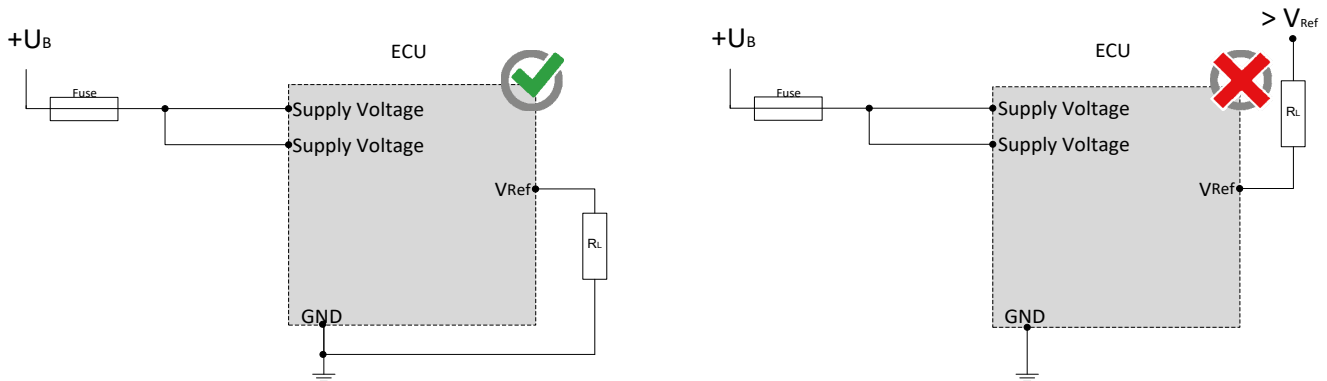


To comply with the IP protection class, the wiring harness attached to the mating connector must be routed through the corrugated tube and the mating connector must be connected to the control unit. The protection cap is then closed over the mating connector and the corrugated tube.

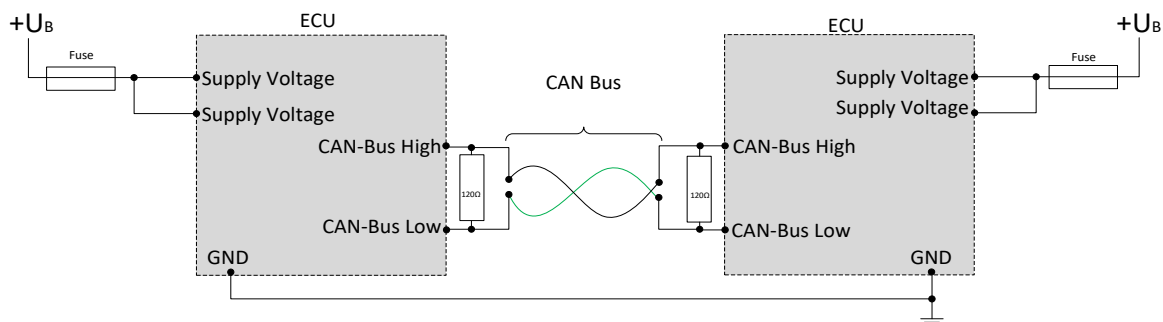
Hightside outputs may only be switched to ground.



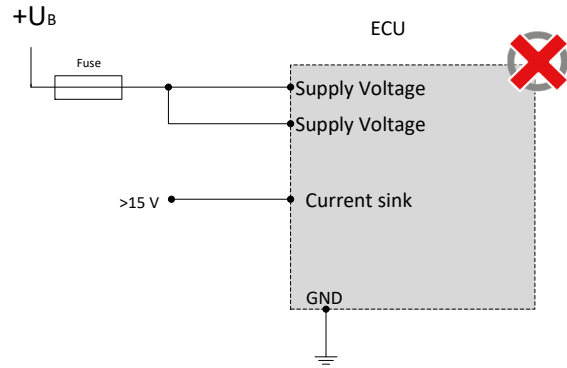
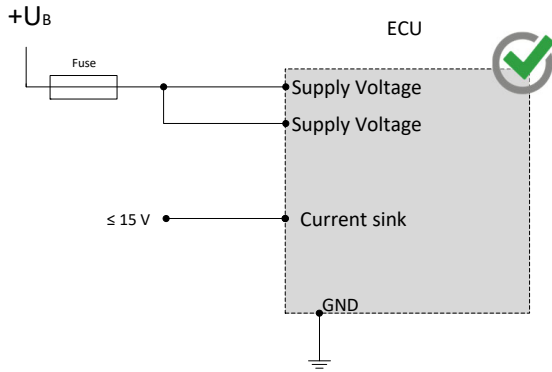
The sensor supplies can be “lifted” through an external circuitry, for example the creation of higher voltage, as they only work as a voltage source but not as voltage drain. The lift of a voltage source may lead to unforeseen malfunctions and damages of the control unit in case of permanent operation.



CAN bus communication is the main communication between the control unit and the vehicle. Therefore, connect the CAN bus with special care and check the correct communication with the vehicle to avoid undesired behavior.



When using the input with pull-down resistance (using DOM_PD), you must not connect a greater voltage than 15 V to the input.



SAFETY AND INSTALLATION INFORMATION

It is essential to read the instructions in full thoroughly before working with the device.

Please note and comply with the instructions in the operating instructions and the information in the device data sheet, see www.mrs-electronic.com

Staff qualification: Only staff with the appropriate qualifications may work on this device or in its proximity.

SAFETY



WARNING! Danger as a result of a malfunction of the entire system.

Unforeseen reactions or malfunctions of the entire system may jeopardise the safety of people or the machine.

- Ensure that the device is equipped with the correct software and that the wiring and settings on the hardware are appropriate.



WARNING! Danger as a result of unprotected moving components.

Unforeseen dangers may occur from the entire system when putting the device into operation and maintaining it.

- Switch the entire system off before carrying out any work and prevent it from unintentionally switching back on.
- Before putting the device into operation, ensure that the entire system and parts of the system are safe.
- The device should never be connected or separated under load or voltage.



CAUTION! Risk of burns from the housing.

The temperature of the device housing may be elevated.

- Do not touch the housing and let all system components cool before working on the system.

PROPER USE

The device is used to control or switch one or more electrical systems or sub-systems in motor vehicles and machines and may only be used for this purpose. The device may only be used in an industrial setting.



WARNING! Danger caused by incorrect use.

The device is only intended for use in motor vehicles and machines.

- Use in safety-related system parts for personal protection is not permitted.
- Do not use the device in areas where there is a risk of explosion.

Correct use:

- operating the device within the operating areas specified and approved in the associated data sheet.
- strict compliance with these instructions and no other actions which may jeopardise the safety of individuals or the functionality of the device.

Obligations of the manufacturer of entire systems

It is necessary to ensure that only functional devices are used. If devices fail or malfunction, they must be replaced immediately.

System developments, installation and the putting into operation of electrical systems may only be carried out by trained and experienced staff who are sufficiently familiar with the handling of the components used and the entire system.

It is necessary to ensure that the wiring and programming of the device does not lead to safety-related malfunctions of the entire system in the event of a failure or a malfunction. System behaviour of this type can lead to a danger to life or high levels of material damage.

The manufacturer of the entire system is responsible for the correct connection of the entire periphery (e.g. cable cross sections, correct selection/connection of sensors/actuators).

Opening the device, making changes to the device and carrying out repairs are all prohibited. Changes or repairs made to the cabling can lead to dangerous malfunctions. Repairs may only be carried out by MRS.

Installation

The installation location must be selected so the device is exposed to as low a mechanical and thermal load as possible. The device may not be exposed to any chemical loads.

Install the device in such a manner that the plugs point downwards. This means condensation can flow off the device. Single seals on the cables/leads must be used to ensure that no water gets into the device.

Putting into operation

The device may only be put into operation by qualified staff. This may only occur when the status of the entire system corresponds to the applicable guidelines and regulations.

FAULT CORRECTION AND MAINTENANCE



NOTE The device is maintenance-free and may not be opened.

- If the device has damage to the housing, latches, seals or flat plugs, it must be taken out of operation.

Fault correction and cleaning work may only be carried out with the power turned off. Remove the device to correct faults and to clean it.

Check the integrity of the housing and all flat plugs, connections and pins for mechanical damage, damage caused by overheating, insulation damage and corrosion. In the event of faulty switching, check the software, switches and settings.

Do not clean the device with high pressure cleaners or steam jets. Do not use aggressive solvents or abrasive substances.